

# **Optimal Monitoring Network Design in River Networks**

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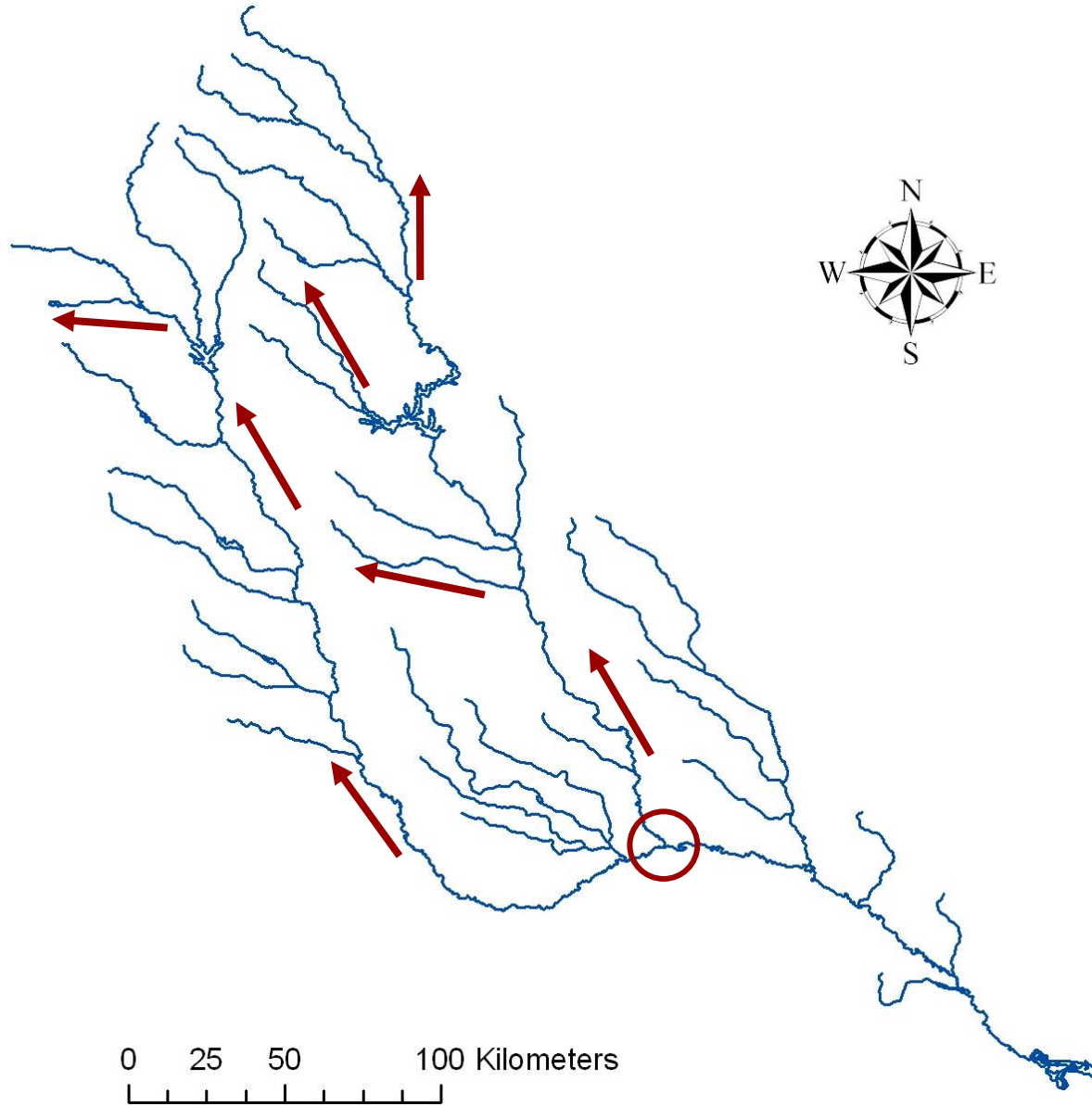
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**School of Civil and Environmental Engineering  
Georgia Institute of Technology, Atlanta, GA**



# Historical Problem Analyzed: Prospecting



# More Recently: Contaminant Monitoring Systems

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- **Provide sufficient and timely information on the quality of the river water to decision makers;**
- **Rapid identification of pollutant sources;**
- **Provide for immediate precautions after a deliberate or accidental spill.**

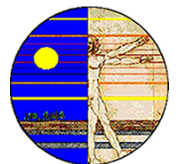
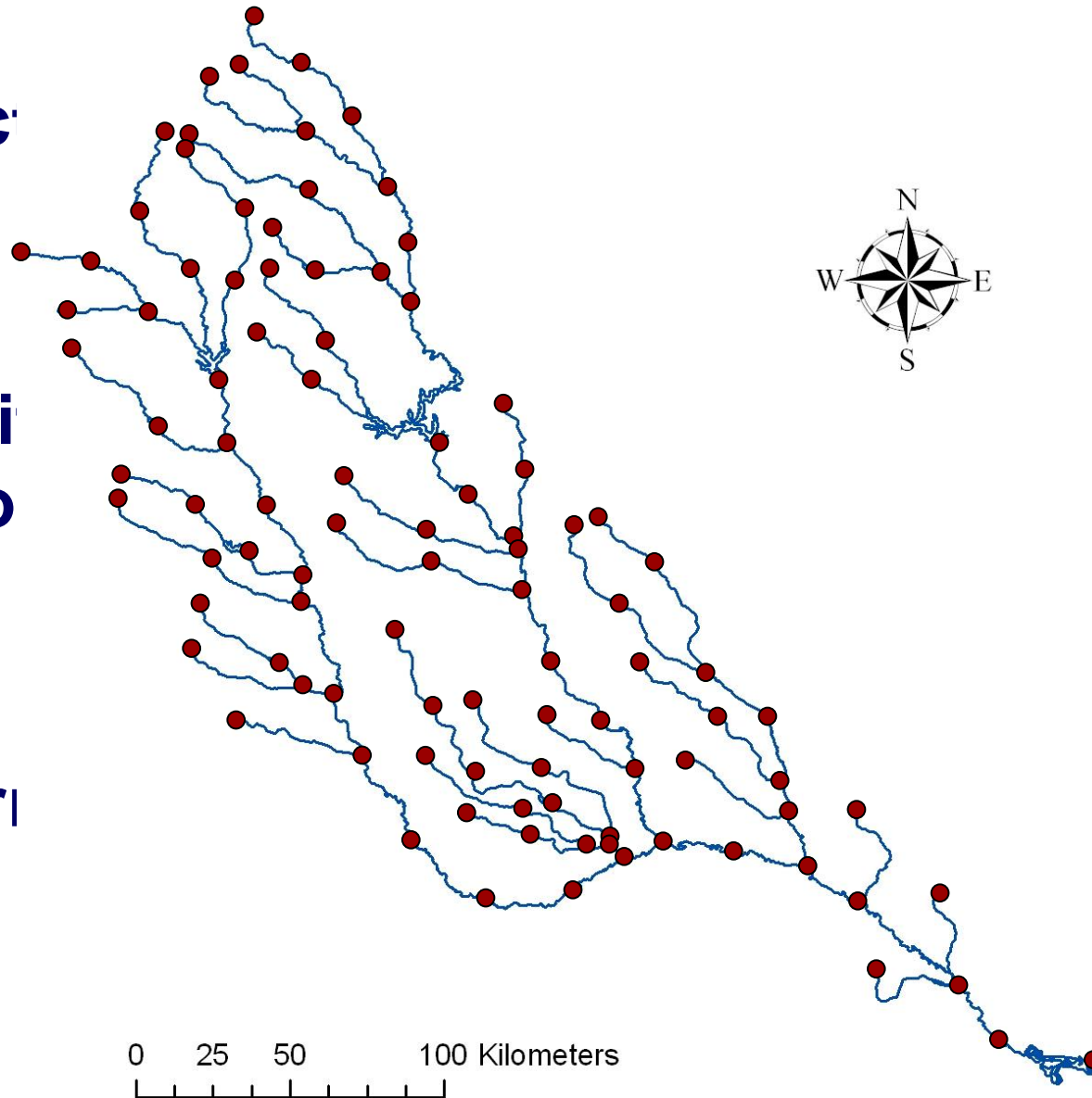


# Design of Monitoring Systems:

- **Selec**

- **Identi  
statio**

- **Deteri**

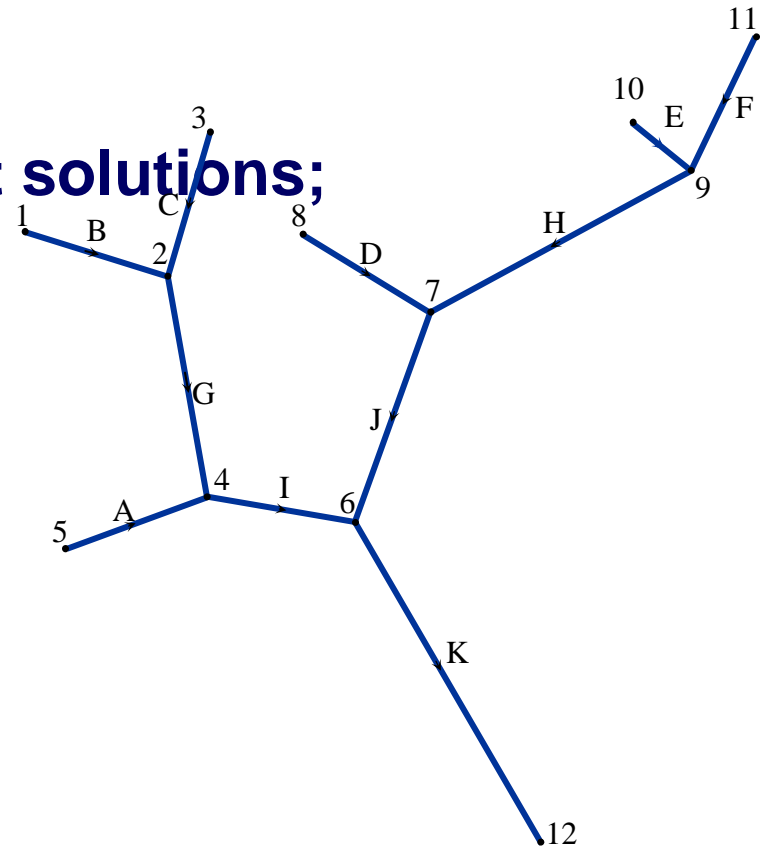


# Previous studies:

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## Based on:

- **Steady state flow and transport solutions;**
- **Geometry of the river network (prospecting applications);**



# Objectives:

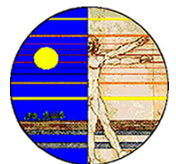
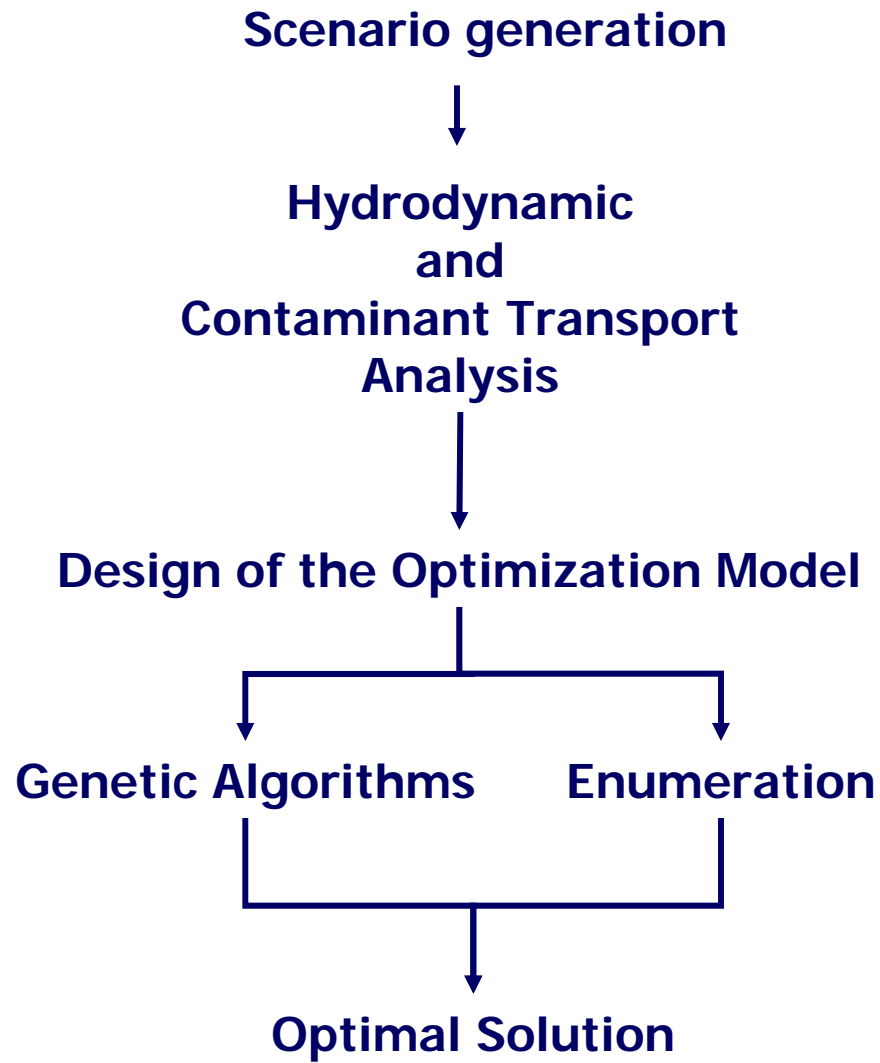
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- **Determination of the optimal monitoring locations based on transient hydrodynamic and contaminant transport analysis;**
- **Comparison of the results of the proposed methodology with a recent study published in the literature;**
- **Purpose is to emphasize the effects of hydraulic and watershed characteristics on the optimal solution.**
- **Large scale application (Altamaha River System)**



# Methodology:

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# **Hydrodynamics and Contaminant Transport:**

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- **Use of a dynamic rainfall-runoff model for the simulation of runoff quantity and quality;**
- **Handle networks of unlimited network size;**
- **Use of a wide variety of standard and natural open channel geometries, and spatially variable hydraulic parameters;**
- **User defined external flows and water quality inputs.**
- **SWMM**





# Performance Measures:

- Average detection time

$$\bar{t}(X) = \frac{1}{S} \sum_{i=1}^S t_i(\hat{X})$$

$$X = [x_1, x_2, \dots, x_M]^T$$

$$t_i(\hat{X}) = \min \{d_i^1(X), d_i^2(X), \dots, d_i^M(X)\}; i = 1, 2, 3, \dots, S$$

$d_i^m(X)$ : detection time of the  $m^{\text{th}}$  monitoring station for scenario  $i$ .

$S$ : total number of scenarios.

$M$ : total number of monitoring stations.

$x_m$ : index of the candidate junction for  $m^{\text{th}}$  monitoring station.

Penalty : for a non-detected scenario,  $t_i(\hat{X}) = \text{Simulation time}$  .



# Performance Measures:

- **Detection Likelihood**

$$R(X) = \frac{1}{S} \sum_{i=1}^S \left( \frac{1}{N_e} \sum_{k=1}^{N_e} \delta_k(\hat{X}) \right)_i$$

$$\delta_k(X) = \begin{cases} 0 & \text{if } k^{\text{th}} \text{ contamination is not detected,} \\ 1 & \text{if } k^{\text{th}} \text{ contamination is detected.} \end{cases}$$

$N_e$  : total number of contamination events within a scenario.



# Optimization Model:

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$$f_1 = \underset{X}{\text{Minimize}} \left\{ \bar{t} \left( \hat{X} \right) \right\}$$

$$f_2 = \underset{X}{\text{Maximize}} \left\{ R \left( \hat{X} \right) \right\}$$

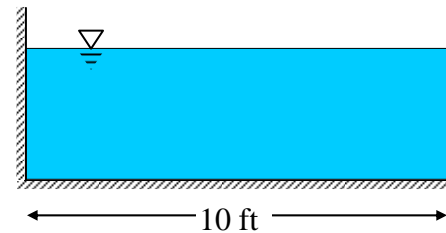
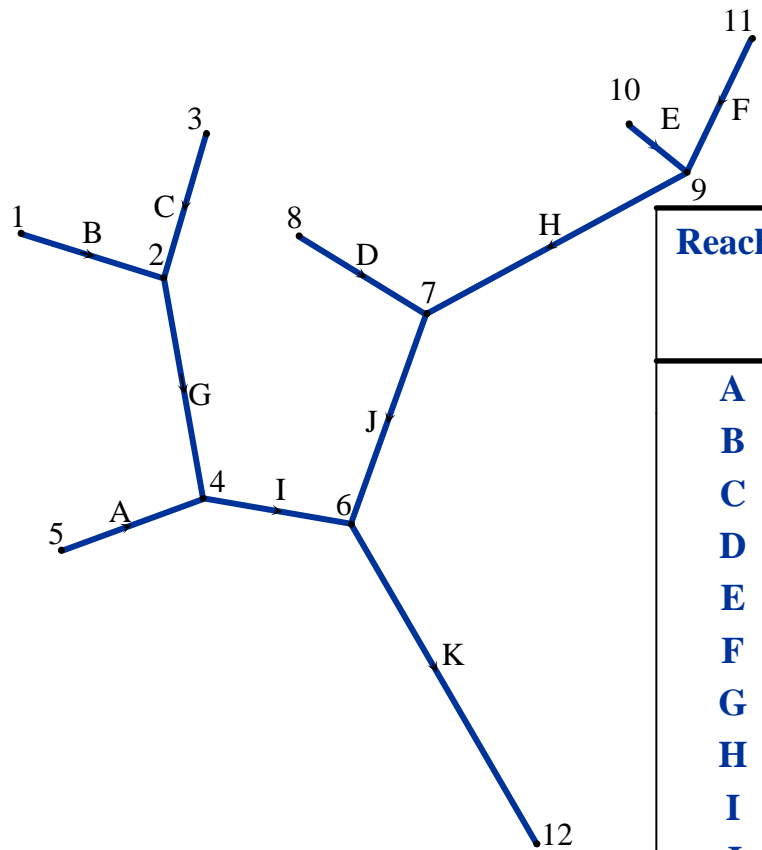
$$s.t. M = M_o$$

$M_o$  : total number of monitoring sites.



# Application:

## Hypothetical River Network



Reach	Length (ft)	Flow rate (ft <sup>3</sup> /s)	Depth (ft)	Width (ft)	Channel slope	Manning's n
A	2000	10	1.31	10	0.0001	0.02
B	2000	10	1.31	10	0.0001	0.02
C	2000	10	1.31	10	0.0001	0.02
D	2000	10	1.31	10	0.0001	0.02
E	1000	10	1.31	10	0.0001	0.02
F	2000	10	1.31	10	0.0001	0.02
G	3000	20	2.08	10	0.0001	0.02
H	4000	20	2.08	10	0.0001	0.02
I	2000	30	2.75	10	0.0001	0.02
J	3000	30	2.75	10	0.0001	0.02
K	5000	60	4.53	10	0.0001	0.02

Three monitoring stations at junctions:

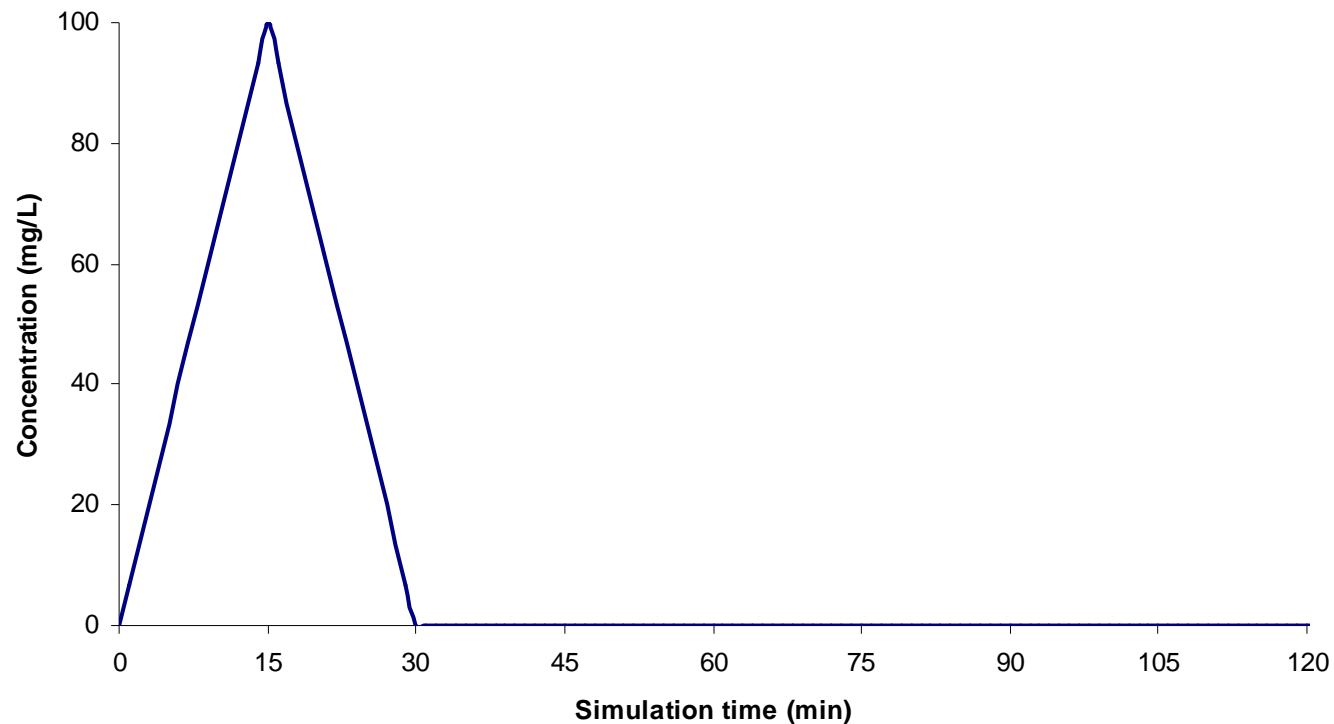
$$\binom{12}{3} = 220 \quad \text{possible placements}$$



# Application:

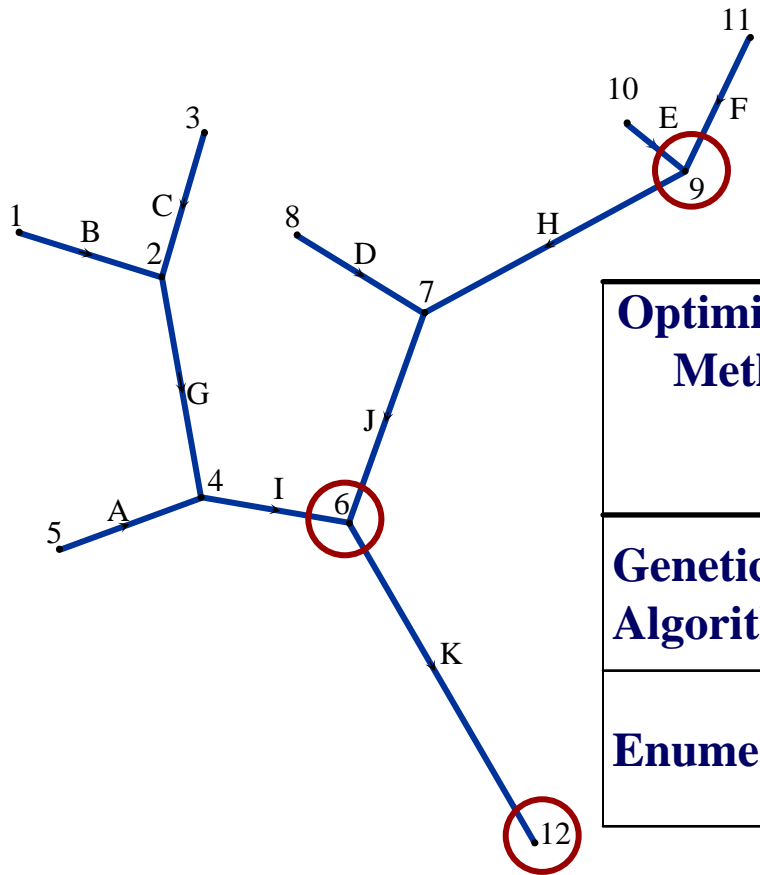
## Case 1 Scenario: Single contamination at any junction

- Total number of scenarios,  $S = 12$ ;
- Simulation time: 4 days;
- Contamination occurs at the beginning of simulation.

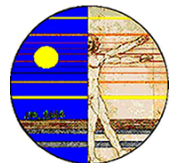


# Application:

## Case 1: Results

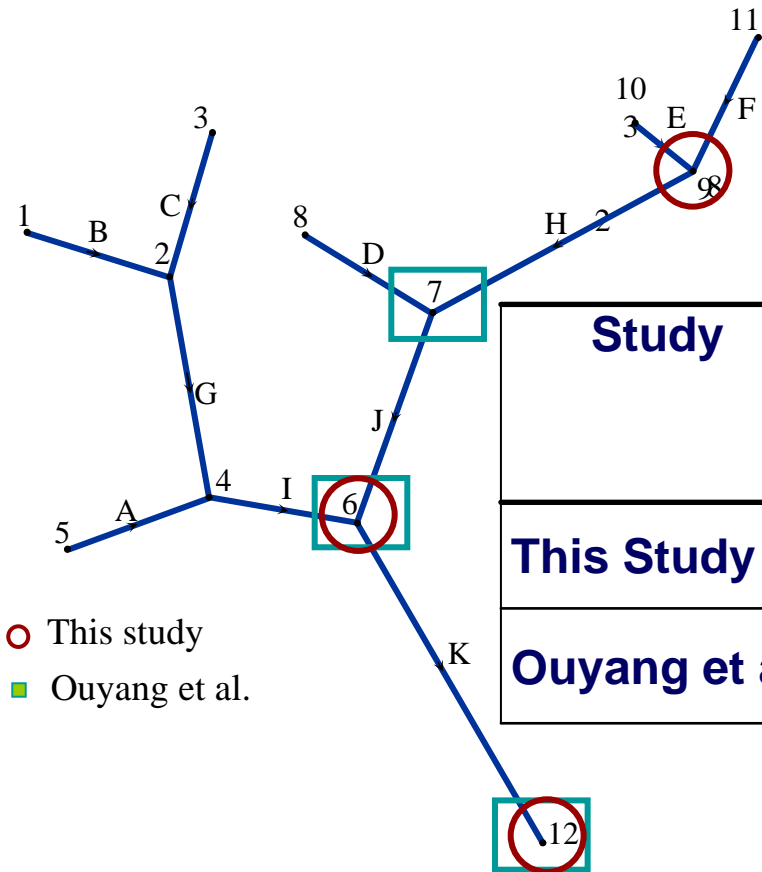


Optimization Method	Optimum Sensor Locations	Average Detection Time (min)	Reliability (%)
Genetic Algorithm	6 – 9 – 12	63.75	100
Enumeration	6 – 9 – 12	63.75	100



# Application:

## Comparison for Case 1 with Ouyang et al.

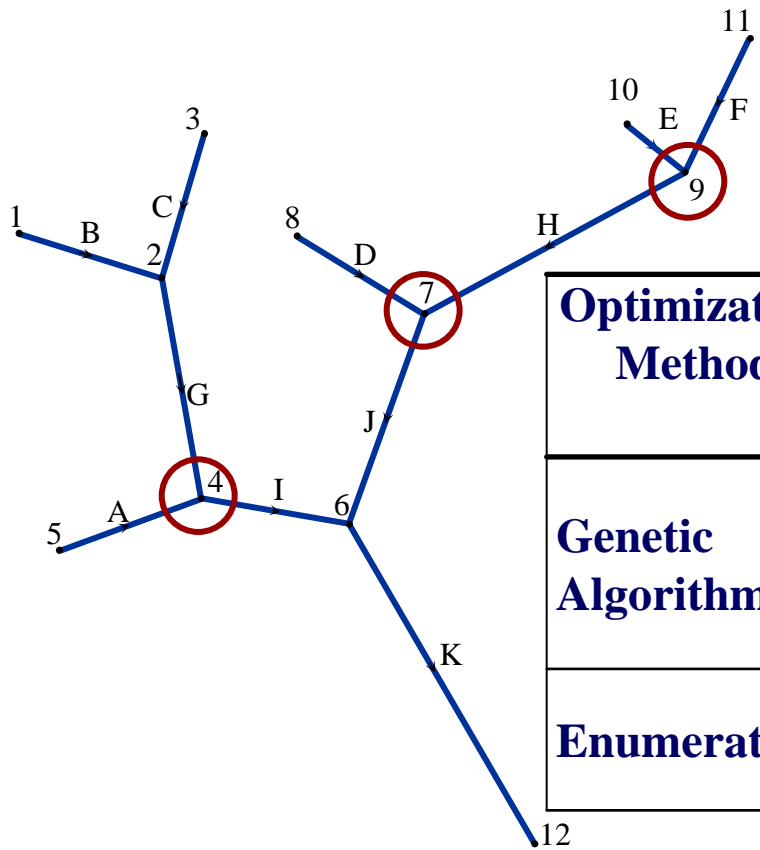


Study	Optimum Sensor Locations	Average Detection Time (min)	Reliability (%)
This Study	6 – 9 – 12	63.75	100
Ouyang et al.	6 – 7 – 12	72.50	100



# Application: (an inferior solution)

## Case 1: Results



Optimization Method	Optimum Sensor Locations	Average Detection Time (min)	Reliability (%)
Genetic Algorithm	4 – 7 – 9	1000	83
Enumeration	4 – 7 – 9	1000	83





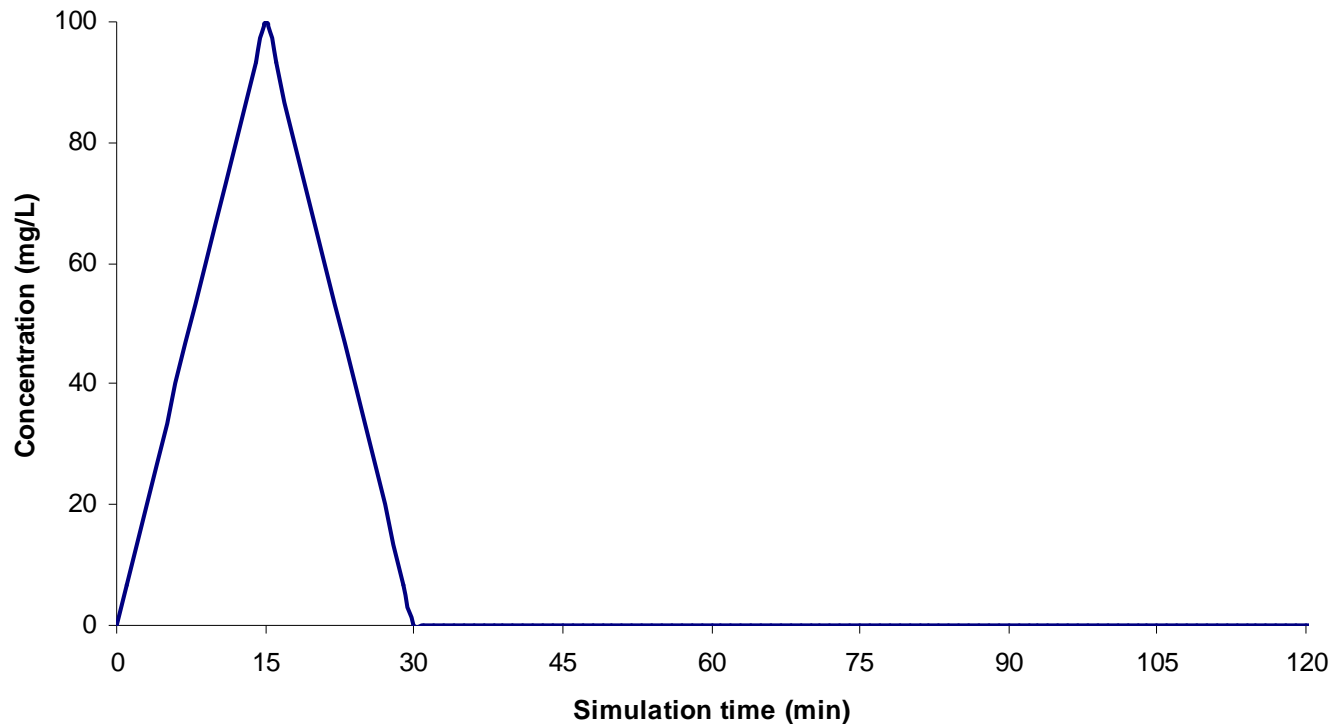
# Application:

## Case 2: Two simultaneous spills at distinct junctions

- Total number of scenarios;

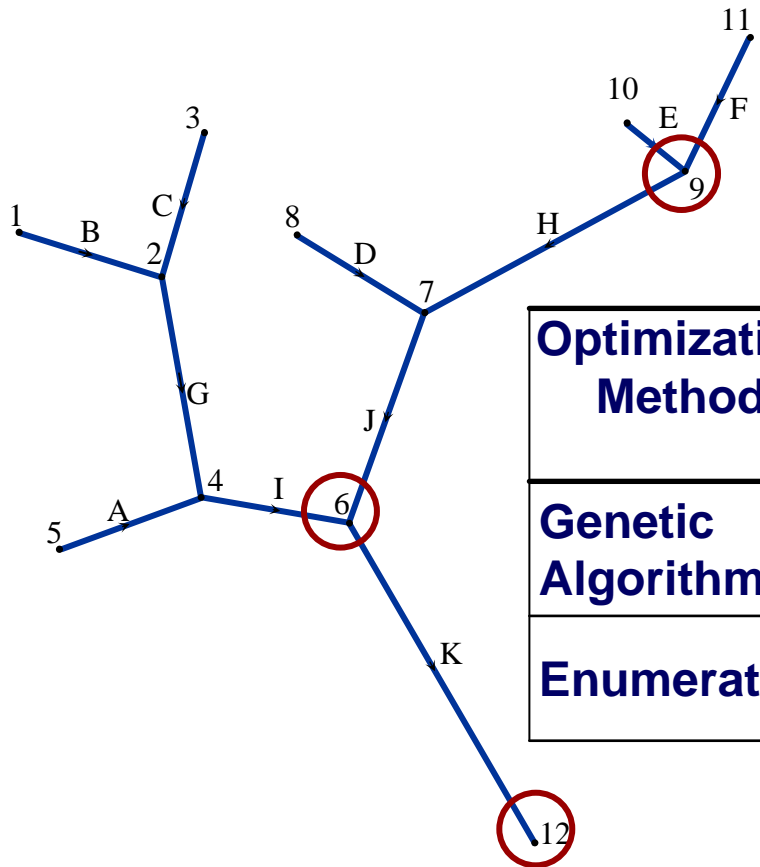
$$S = \binom{12}{2} = 66$$

- Simulation time: 4 days;
- Contamination occurs at the beginning of simulation.



# Application:

## Case 2: Results



Optimization Method	Optimum Sensor Locations	Average Detection Time (min)	Reliability (%)
Genetic Algorithm	6 – 9 – 12	37.73	100
Enumeration	6 – 9 – 12	37.73	100

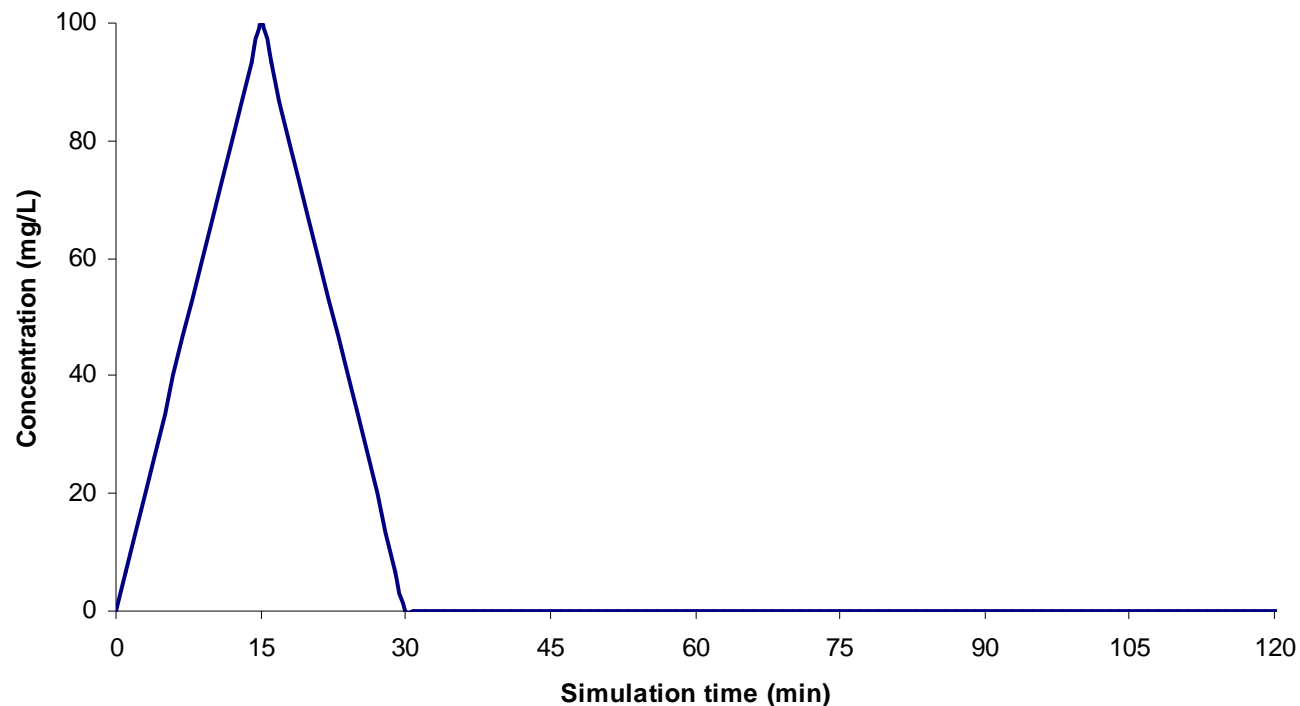


# Application:

## Case 3: Two spills with a 15 min time lag

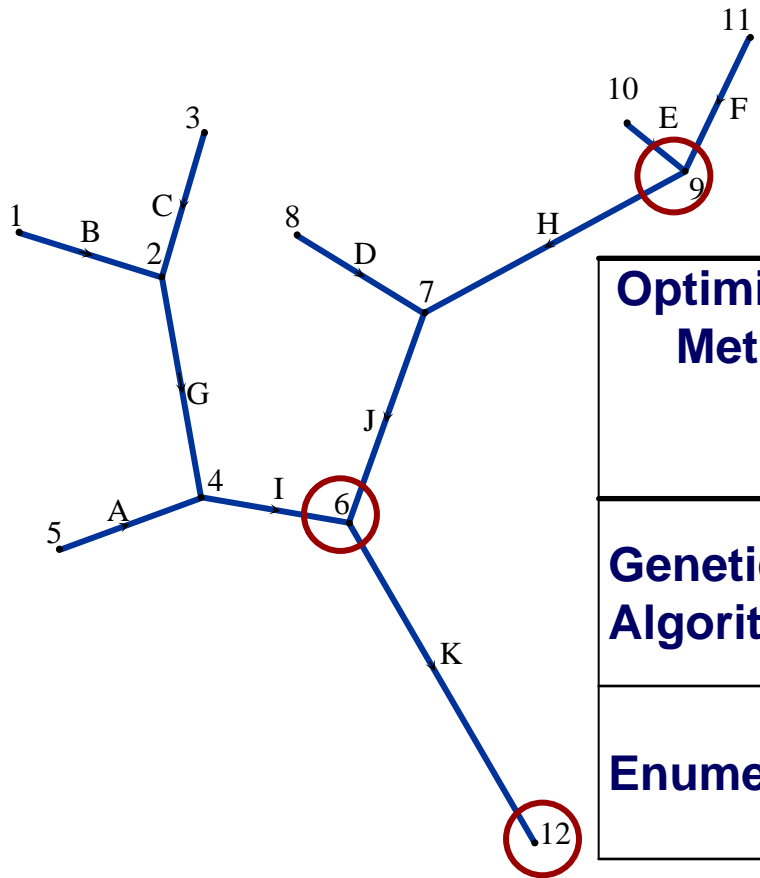
- Total number of scenarios;
- Simulation time: 4 days;
- First spill occurs at the beginning of simulation.

$$S = 2 \binom{12}{2} = 132$$

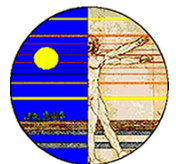


# Application:

## Case 3: Results

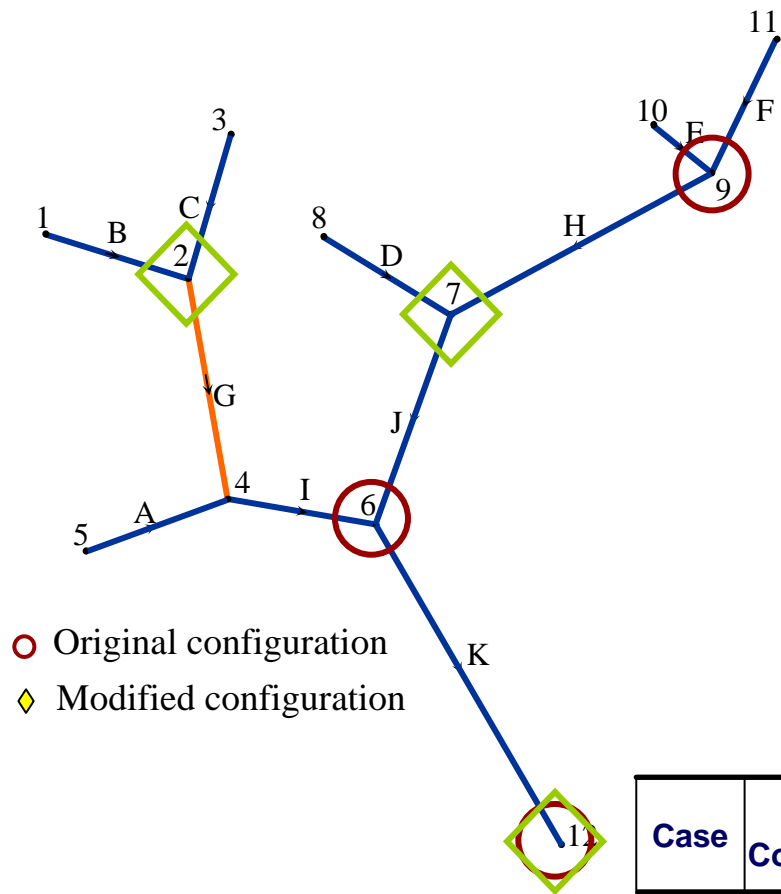


Optimization Method	Optimum Sensor Locations	Average Detection Time (min)	Reliability (%)
Genetic Algorithm	6 – 9 – 12	44.55	100
Enumeration	6 – 9 – 12	44.55	100



# Application:

## Emphasis on hydraulic characteristics



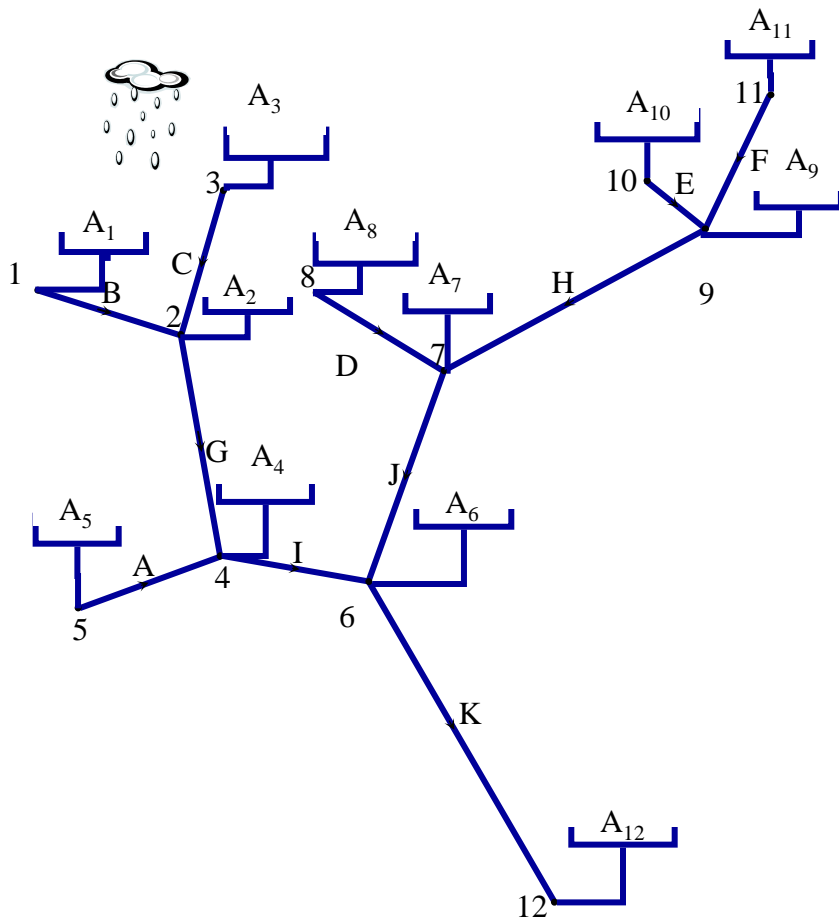
Reach	Length (ft)	Flow Rate (ft <sup>3</sup> /s)	Depth (ft)	Width (ft)	Channel Slope	Manning n
A	2000	10	1.31	10	0.0001	0.02
B	2000	10	1.31	10	0.0001	0.02
C	2000	10	1.31	10	0.0001	0.02
D	2000	10	1.31	10	0.0001	0.02
E	1000	10	1.31	10	0.0001	0.02
F	2000	10	1.31	10	0.0001	0.02
G	3000	20	3.96	10	0.0001	0.05
H	4000	20	2.08	10	0.0001	0.02
I	2000	30	2.75	10	0.0001	0.02
J	3000	30	2.75	10	0.0001	0.02
K	5000	60	4.53	10	0.0001	0.02

Case	Hydraulic Configuration	Optimum Sensor Locations	Average Detection Time (min)	Reliability (%)
1	Original	6 – 9 – 12	63.75	100
	Modified	2 – 7 – 12	70.00	100
2	Original	6 – 9 – 12	37.73	100
	Modified	2 – 9 – 12	39.32	100
3	Original	6 – 9 – 12	44.55	100
	Modified	2 – 9 – 12	46.14	100



# Application:

## Emphasis on watershed characteristics



Catchments	Connected Junction	Area (ac)
A <sub>1</sub>	1	1
A <sub>2</sub>	2	2
A <sub>3</sub>	3	1
A <sub>4</sub>	4	2.5
A <sub>5</sub>	5	1
A <sub>6</sub>	6	2.5
A <sub>7</sub>	7	3
A <sub>8</sub>	8	1
A <sub>9</sub>	9	1.5
A <sub>10</sub>	10	0.5
A <sub>11</sub>	11	1
A <sub>12</sub>	12	2.5

2000 ft → 1 ac

Rainfall intensities : 1, 2 and 3 in/hour

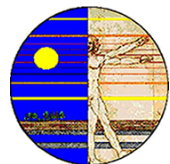
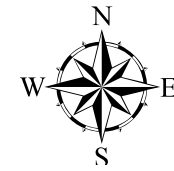
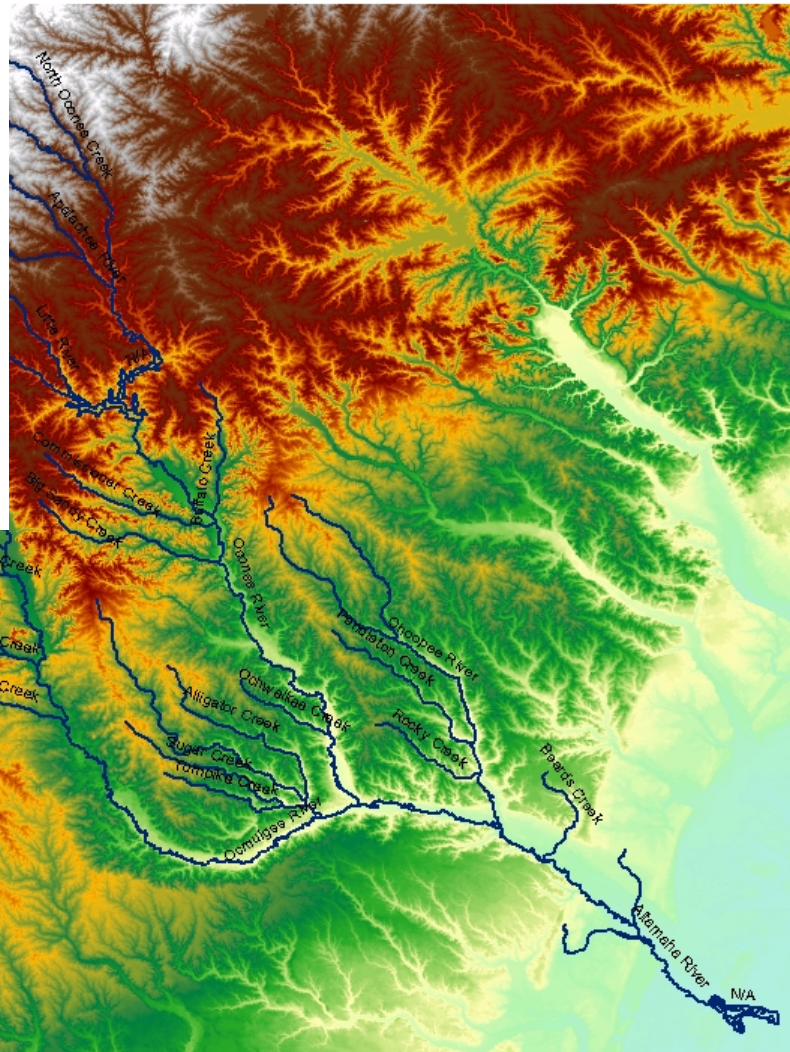
Rainfall duration : 1 hour

Rain Concentration: 10 mg/L

Simulation time : 10 hours

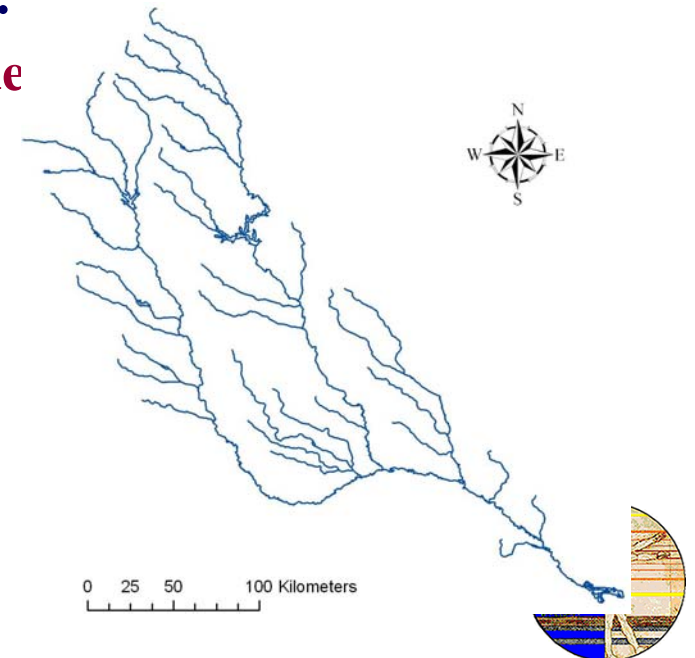


# Altamaha River Basin Application:



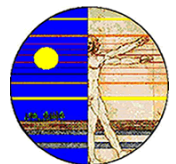
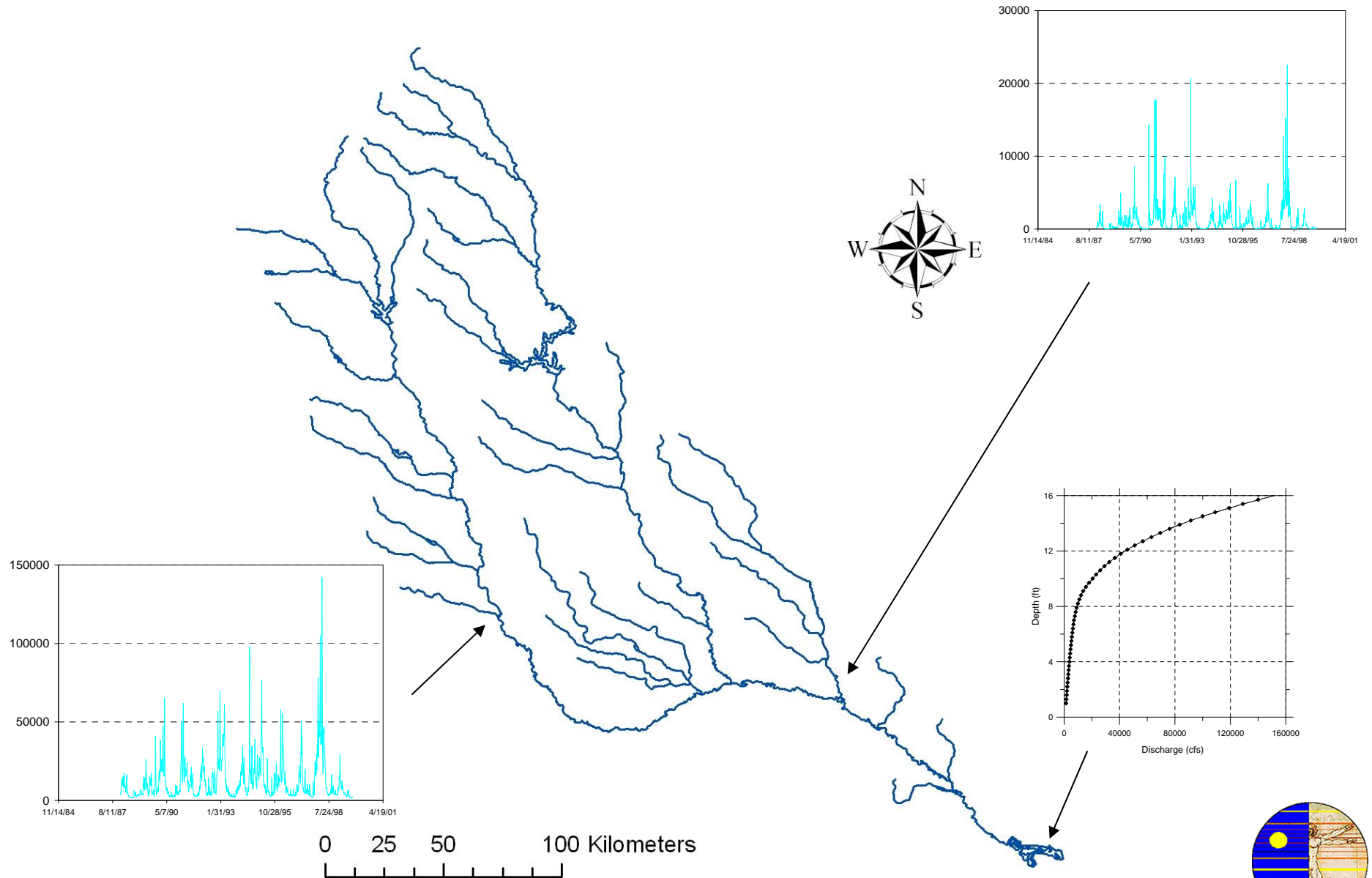
# Altamaha River Network (Assumptions):

- Trapezoidal Channels throughout river network;
  - GIS and USGS based channel geometry data can be included.
- Constant slope for each river reach;
  - GIS and USGS based channel geometry data can be included also other spatially variable parameters can be introduced.
- Transient contaminant transport with fate and dilution effects ;
  - Unsteady rainfall events can be analyzed as demonstrated.
- Single contamination scenarios are considered.
  - Multiple contaminant sources can be considered

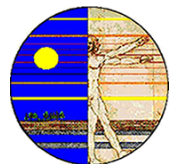
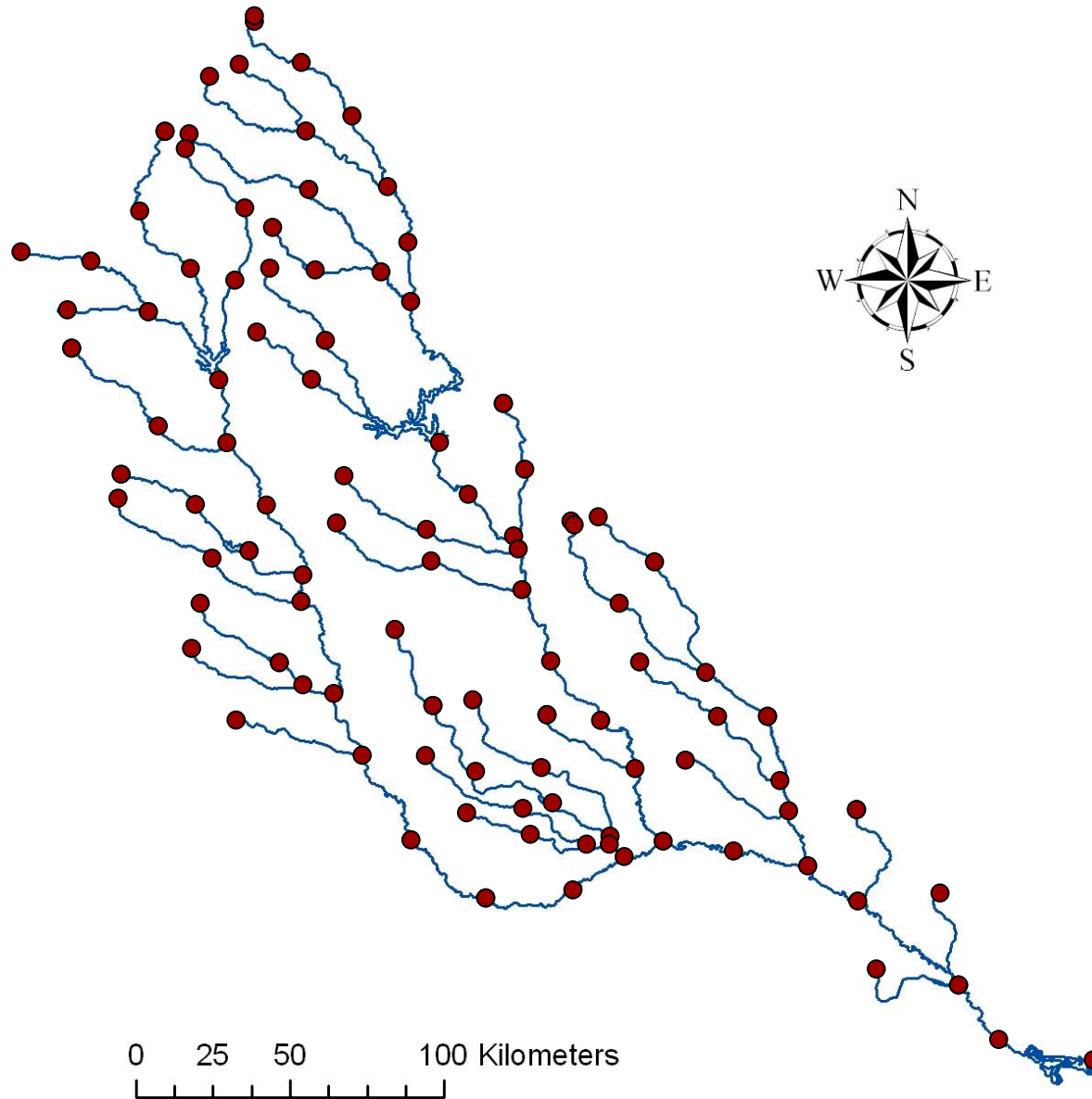




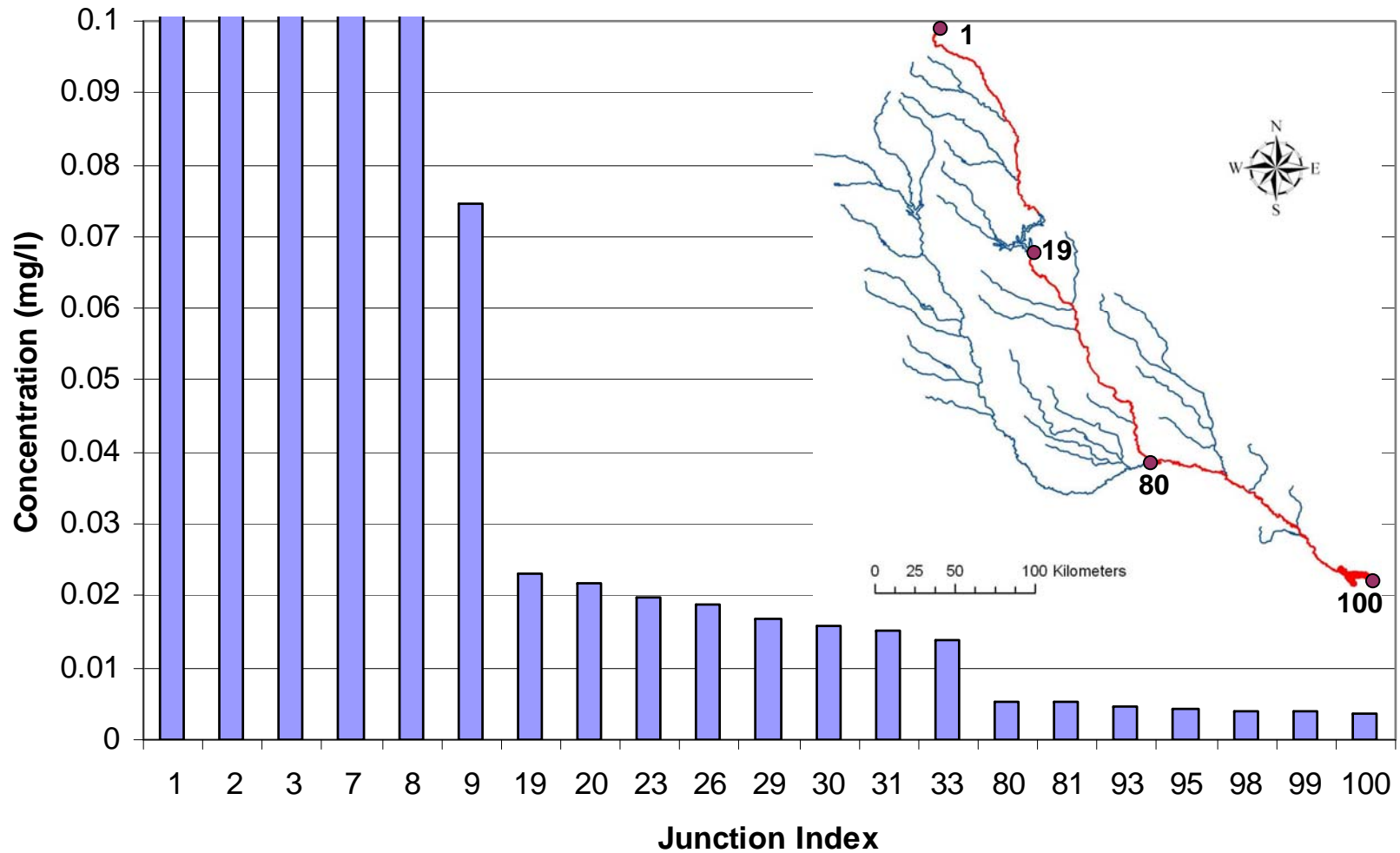
# Flow Calibration:



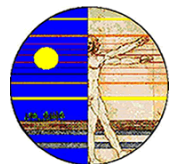
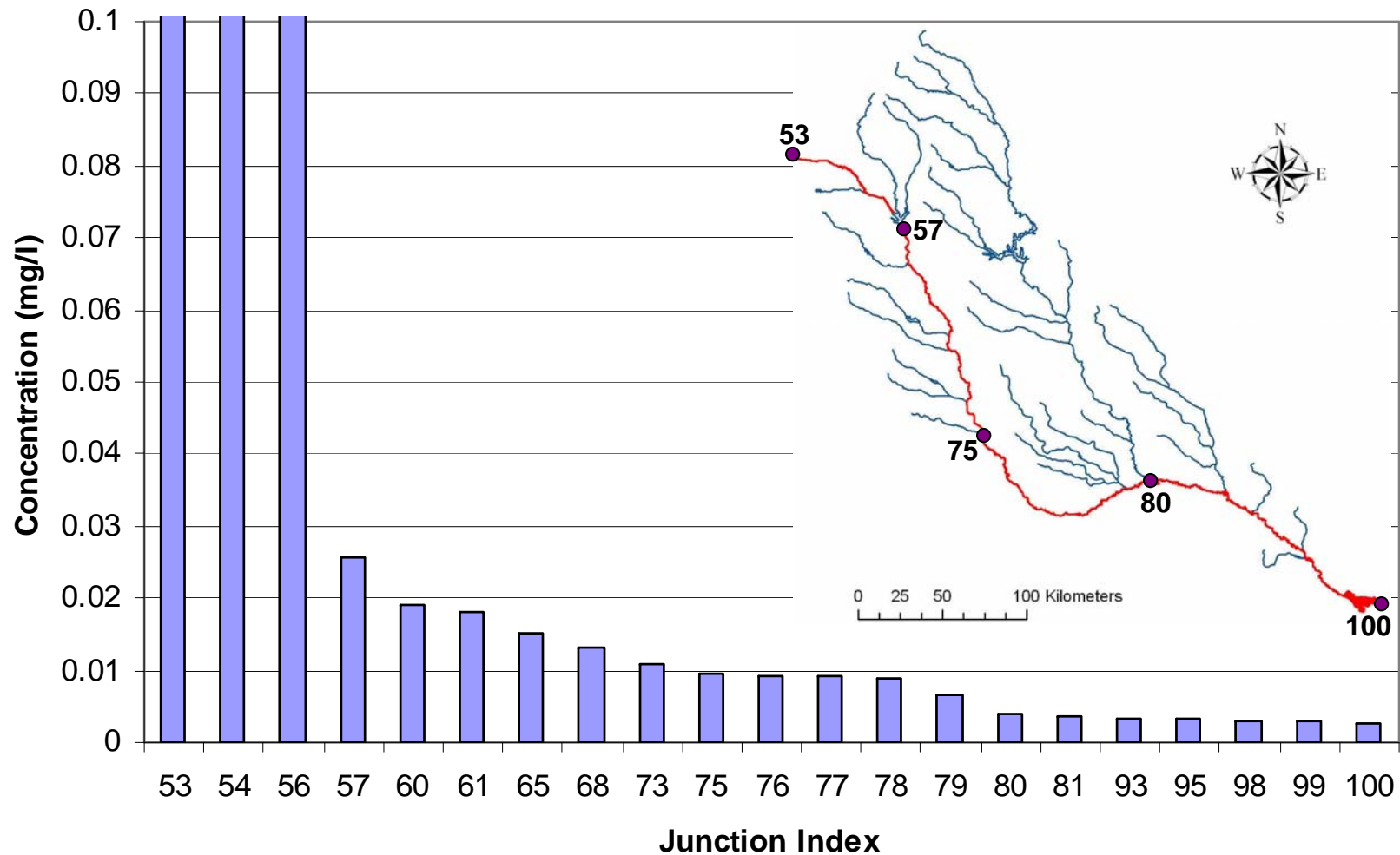
# Altamaha River Network (Scenarios):



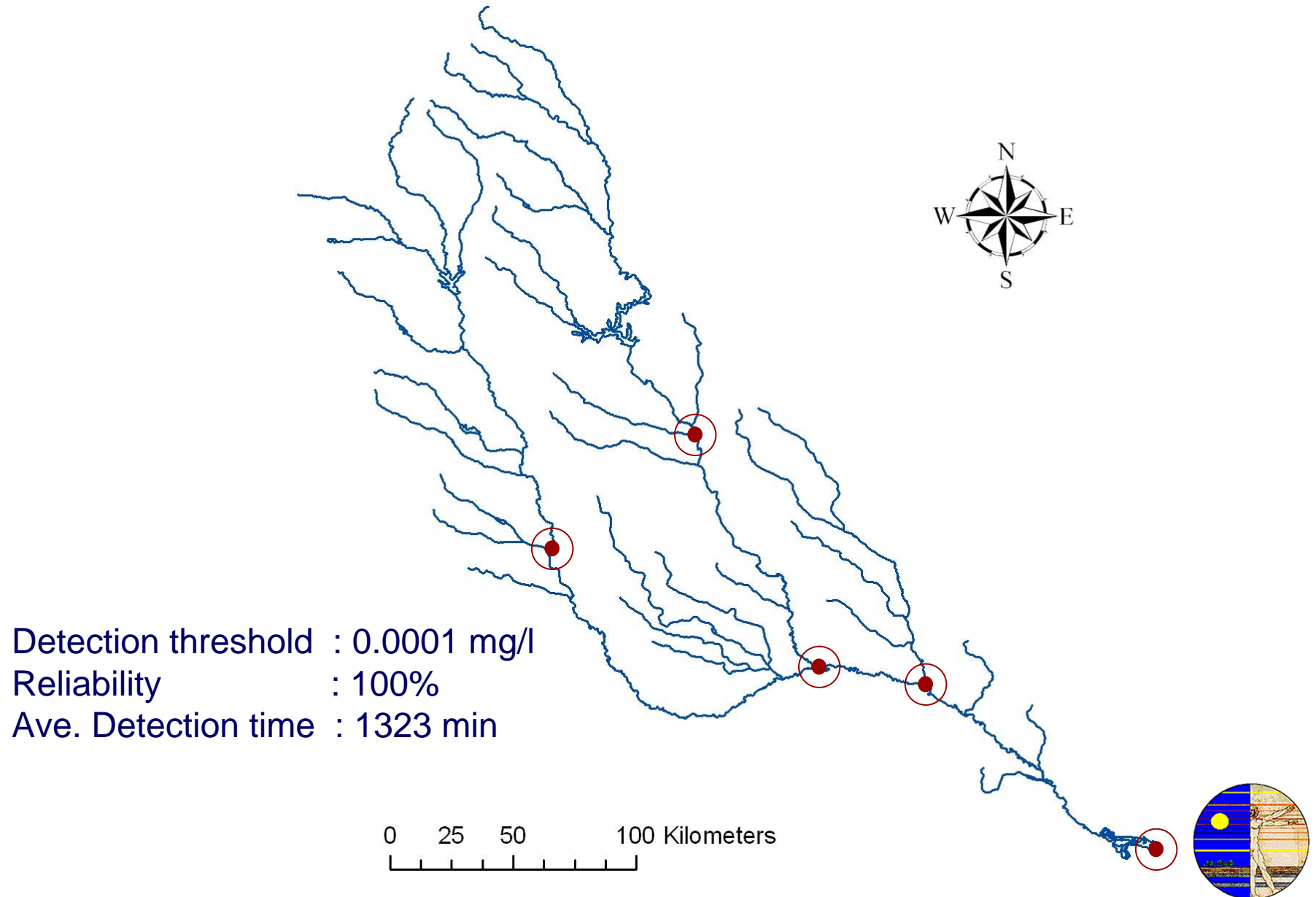
# Altamaha River Network (Breakthrough Curves-1):



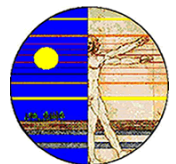
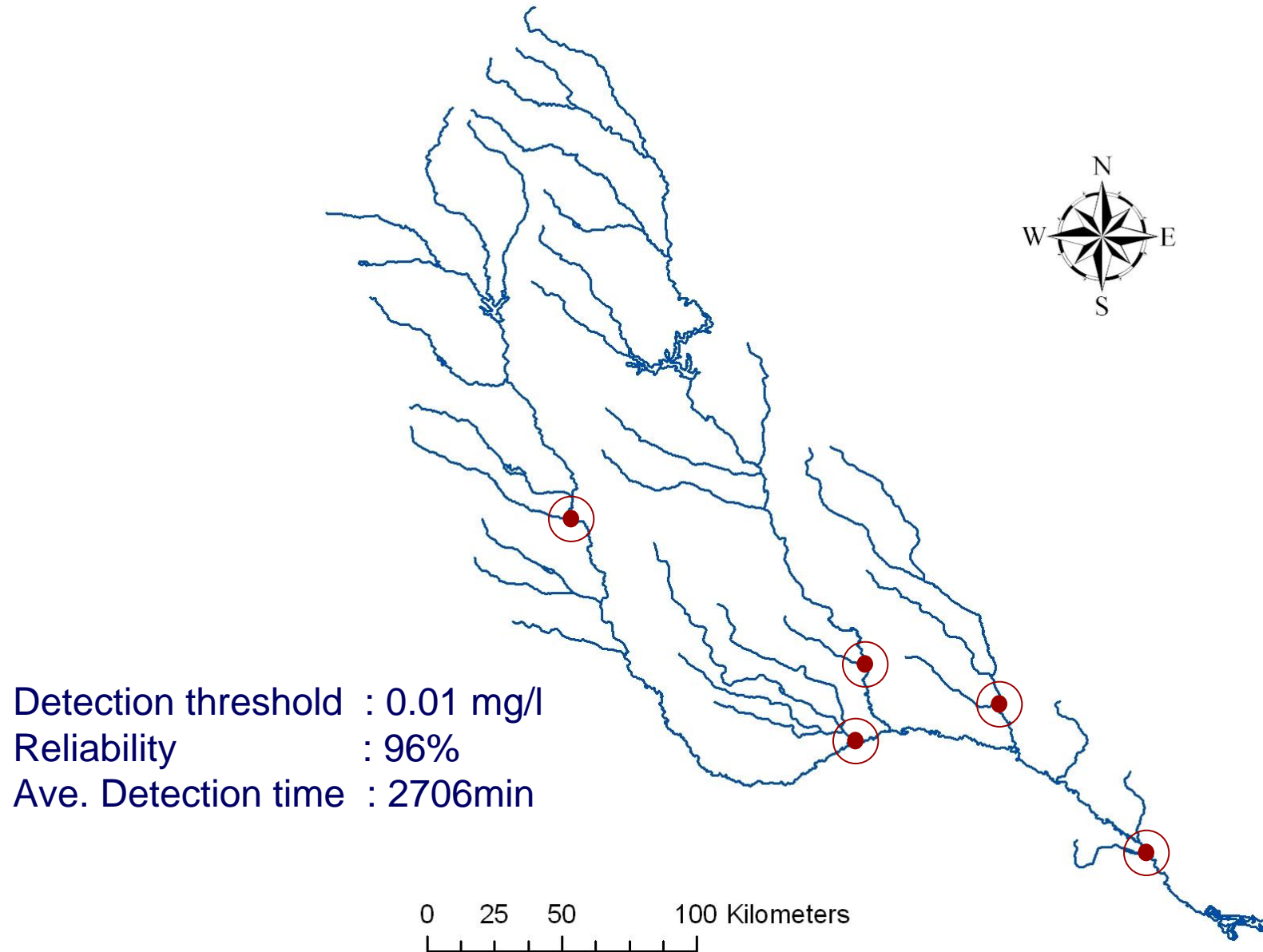
# Altamaha River Network (Breakthrough Curves-2):



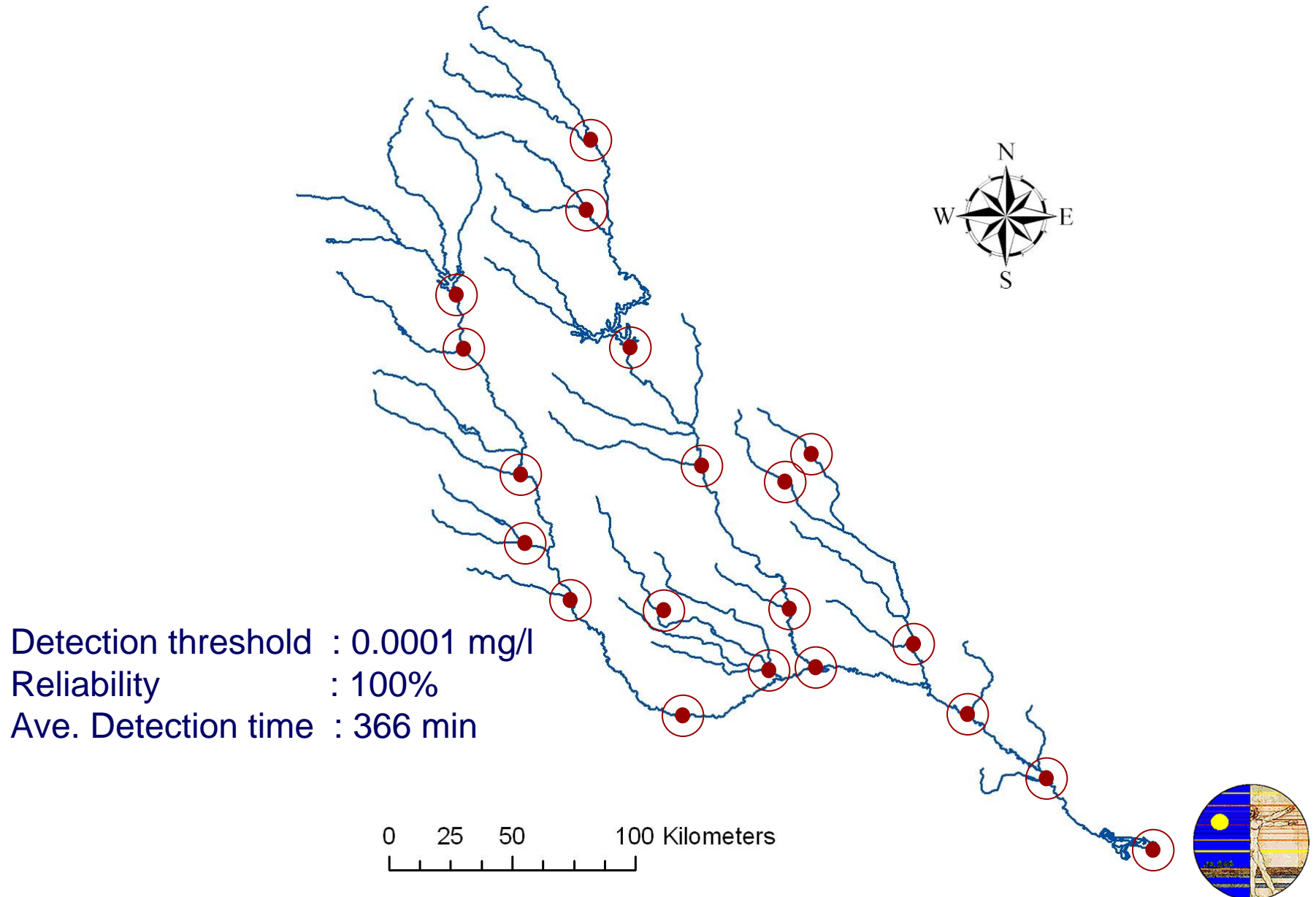
# Altamaha River Network (5 Sensor Solution):



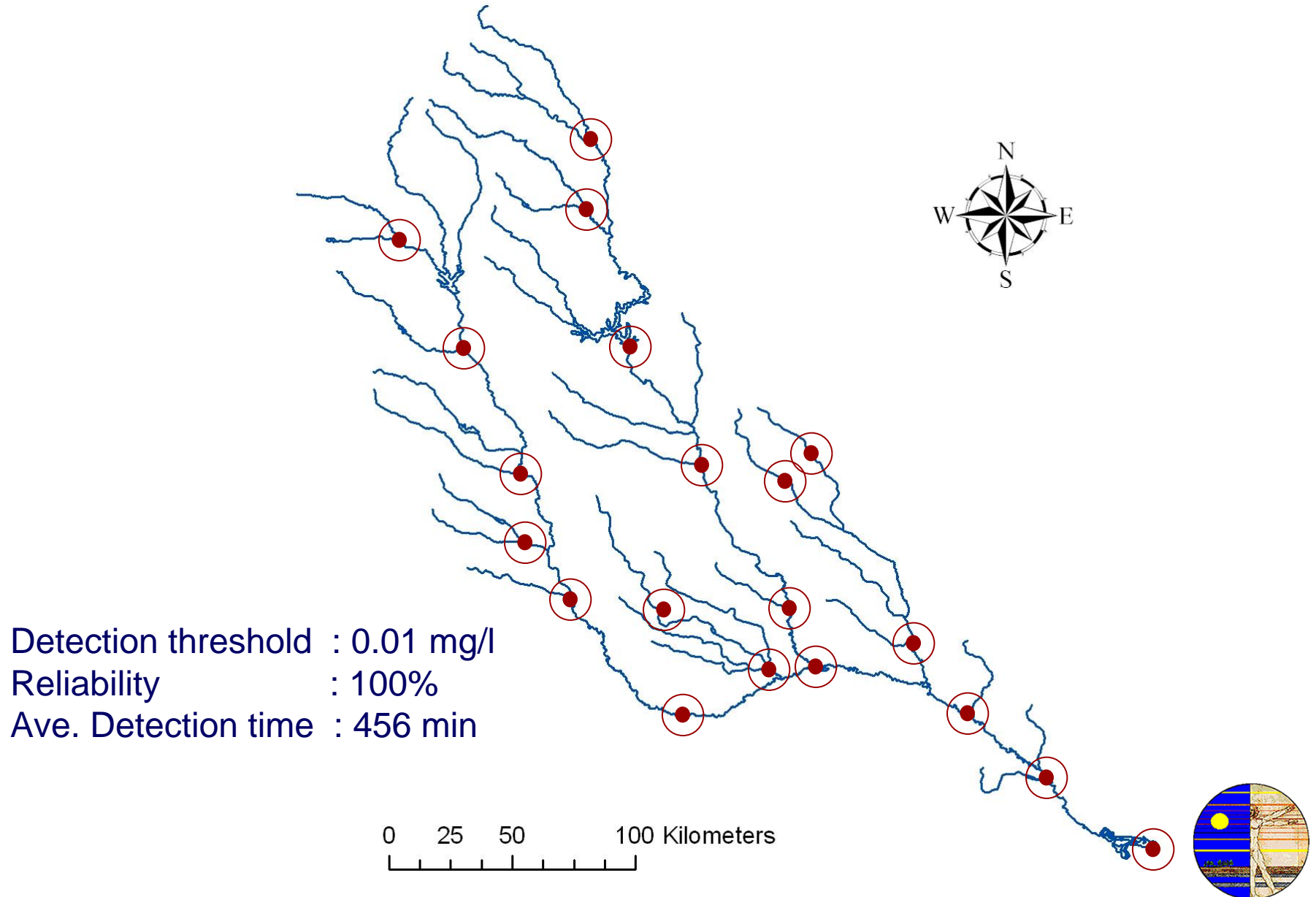
# Altamaha River Network (5 Sensor Solution):



# Altamaha River Network (20 Sensor Solution):

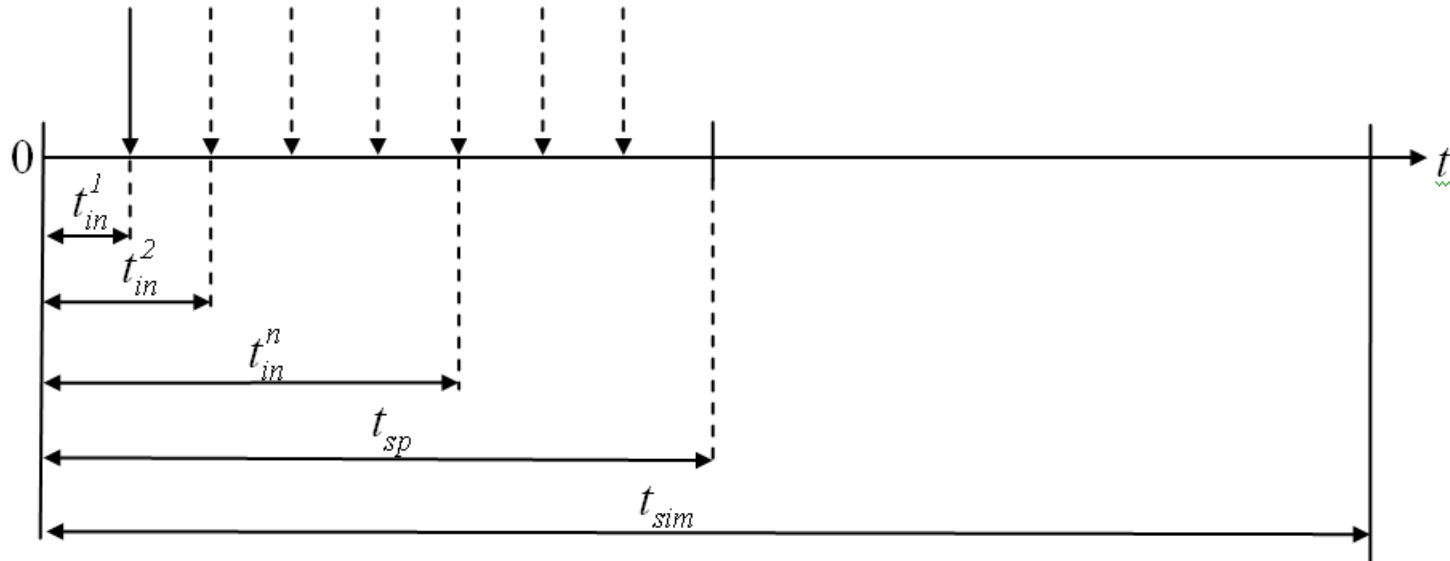


# Altamaha River Network (20 Sensor Solution):





# Altamaha River Network (Pareto Front Analysis)



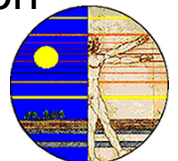
$$t_{dl}^n = t_{sim} - t_{in}^n \quad (\text{max travel time 8 days})$$

$t_{in}^n$  :  $n^{\text{th}}$  selected time of injection.  $n = 1, 2, 3, \dots$

$t_{sp}$  : Time period for possible spills to occur (2 days).

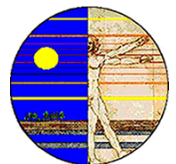
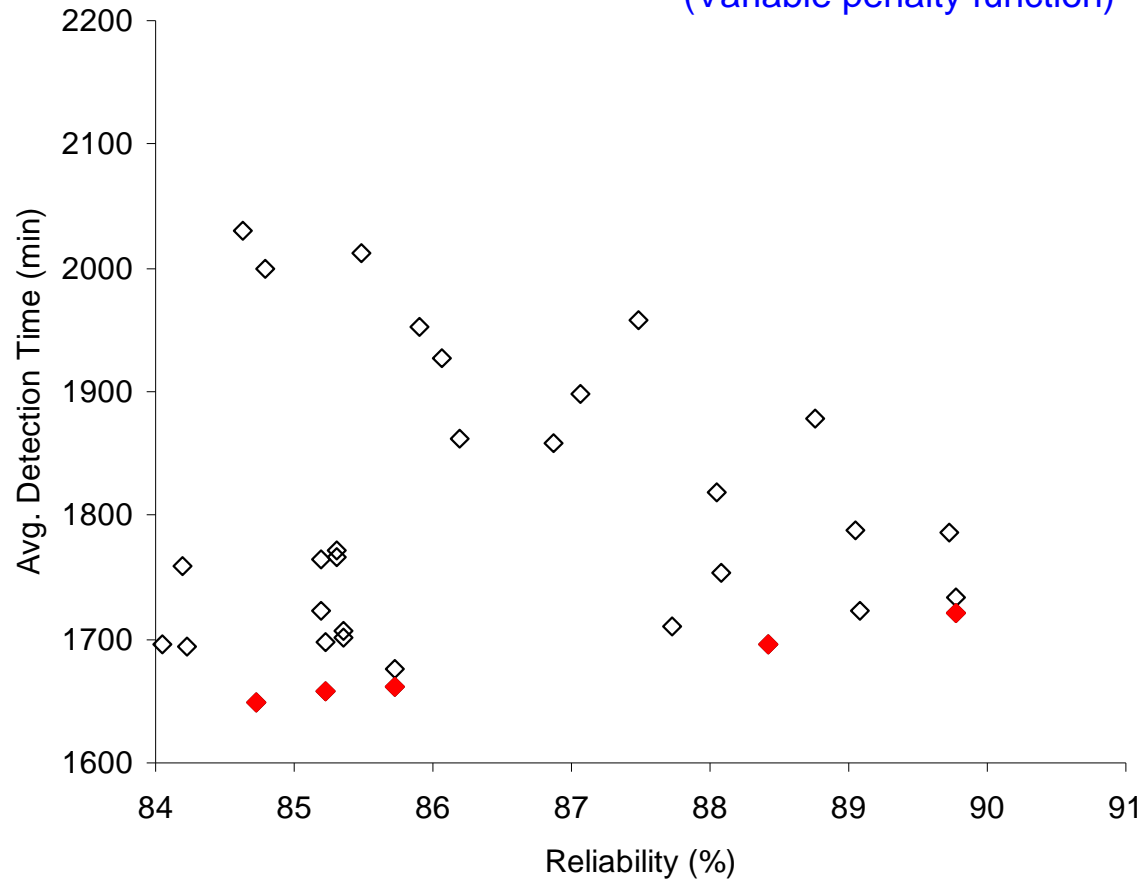
$t_{sim}$  : Simulation time (4 days).

$t_{dl}^n$  : Detection time limit for the scenarios with  $n^{\text{th}}$  selected time of injection and penalty for non-detected contaminations within this set.



# Altamaha River Network (Pareto Front Analysis)

Number of sensors : 5  
Detection threshold : 0.01 mg/l  
Number of nodes spill may occur : 100  
Number of scenarios : 4800  
(Variable penalty function)



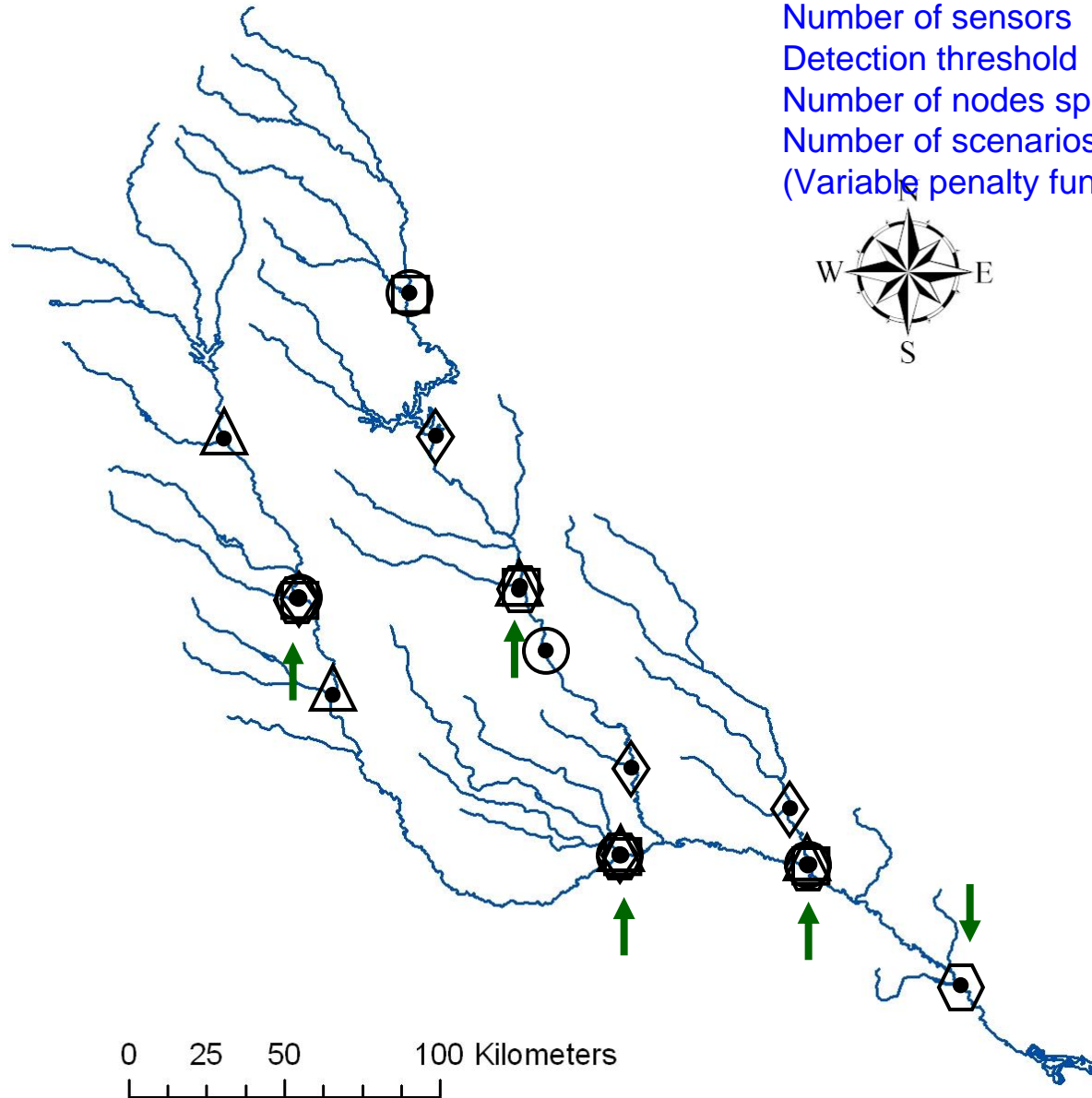
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## Solutions on the Pareto Front

	Avg. Det. Time (min)	Reliability (%)
	1648.8	84.7
	1658.6	85.2
	1662.0	85.7
	1696.0	88.4
	1720.4	89.8



0 25 50 100 Kilometers



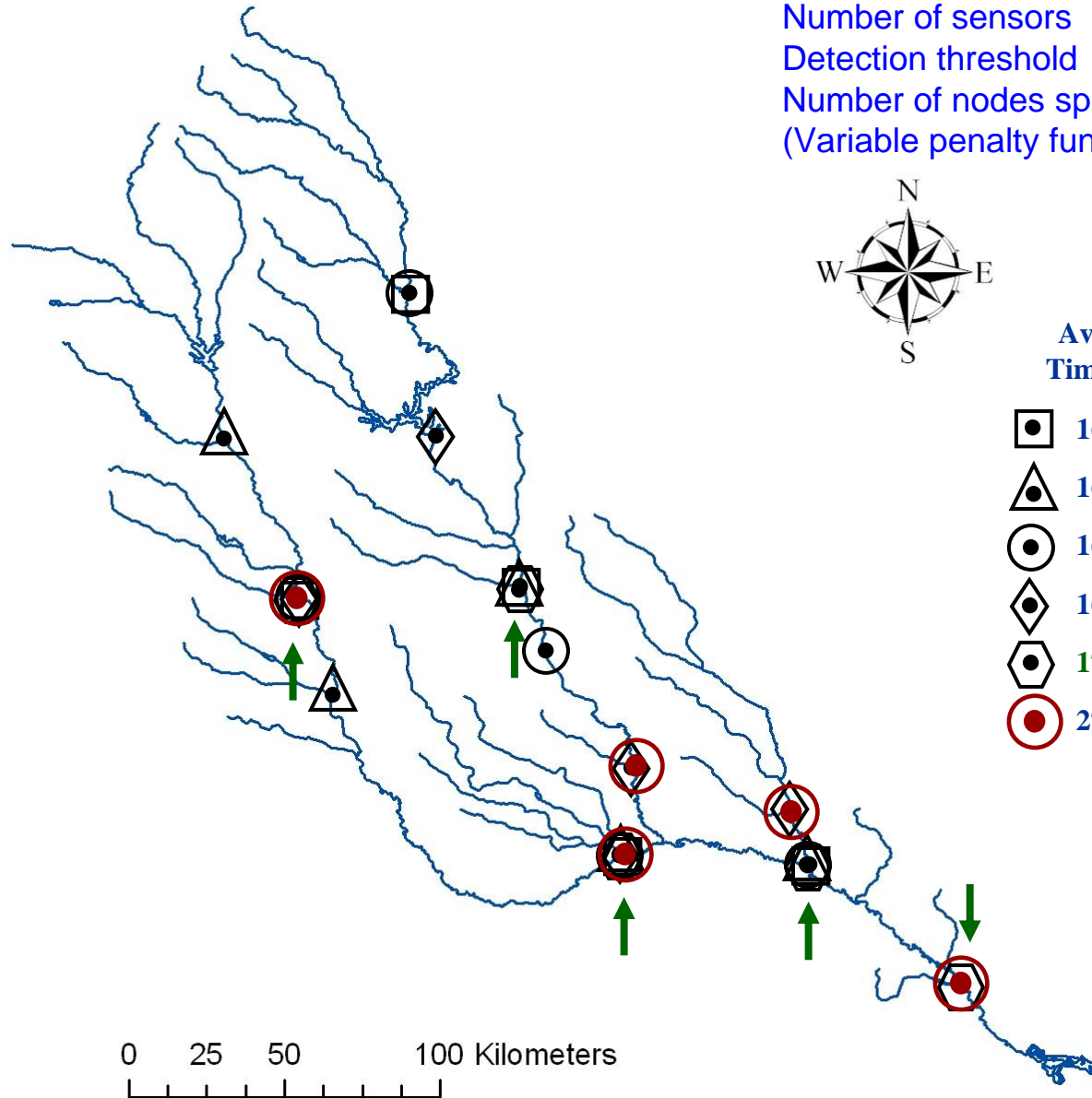
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## Solutions on the Pareto Front

	Avg. Det. Time (min)	Reliability (%)	Number of Scenarios
	1648.8	84.7	4800
	1658.6	85.2	4800
	1662.0	85.7	4800
	1696.0	88.4	4800
	1720.4	89.8	4800
	2705.9	96	100



0 25 50 100 Kilometers



## Conclusions:

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- **Hydrodynamic and watershed characteristics have important impacts on transport of contaminants through a river network which effect the optimal monitoring locations selected.**
- **Optimal monitoring locations highly depend on these factors rather than the geometry of the river system.**
- **If the objective of the monitoring system is to detect contamination in a shorter time, dynamic transport simulation is a crucial step in design.**
- **Representation of the scenarios considered is important.**



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***Thank you...***

